



# Autonomy and Robotics in Marine Renewable Energy

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# Agenda

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- The Offshore Renewable Energy Catapult (OREC) – Intro
- Marine Renewable Energy and applications for Autonomy and Robotics
- Robotics and Autonomous Systems - OREC Testing and Validation
- Technology demonstration and innovation projects

# Our Mission and Vision

## Our mission

*To accelerate the creation and growth of UK companies in the ORE sector*

## Our vision

*By 2030, ORE Catapult will be the world's leading offshore renewables technology centre*

- Centres of Excellence
- Academic Research Hubs  
in partnership with leading universities
- Expanding our assets in Blyth  
and Levenmouth  
the world's foremost open-access  
facilities





# Marine Renewables Energy applications

Offshore wind is growing.....

United Kingdom

- 2020 Operational Turbines

Rest of Europe

- 2470 Operational Turbines

Globally

- 5046 Operational Turbines



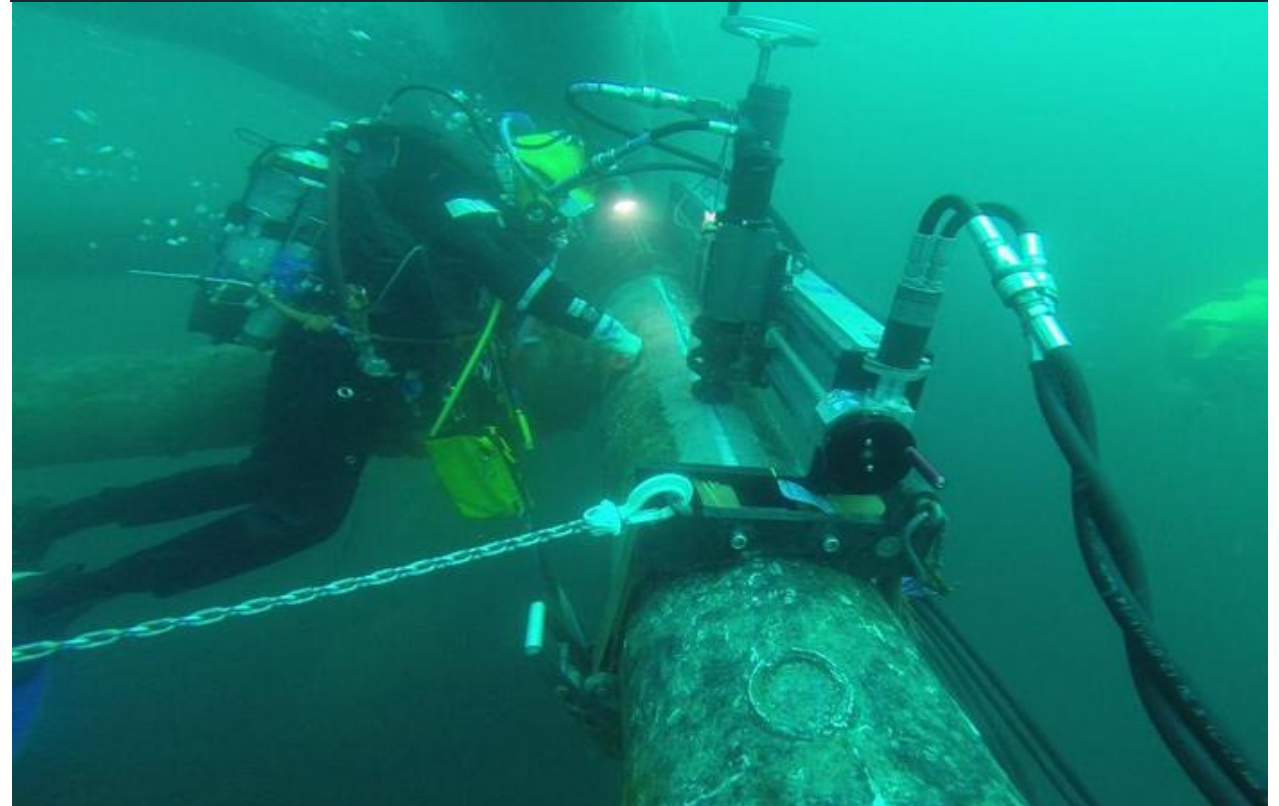
- There are several aspects of the foundation that are of interest in terms of inspection:
  - Internal corrosion of monopile foundations
  - Scour, including
    - Local scour around foundations and cables
    - Global scour in the wind farm
  - Subsea weld integrity
  - Fatigue Crack Growth
- All of these currently are, or have the potential to be carried out by underwater vehicles.



# Things are changing!

- Robotics and autonomous systems have a huge potential to disrupt practices
- Engagement with operators (and turbine manufacturers) shows strong interest in reducing usage of expensive divers which carry large health and safety risk
- Underwater robotic solutions can reduce costs
  - Enable more proactive monitoring & inspection – better understanding of what is happening on site

*"Doing anything subsea is very expensive, so any activities have to be very well justified"*  
– *Anonymous Wind Farm Operator*





- Larger turbines
  - Greater cost of downtime, each asset is becoming increasingly important
  - Walney Extension has a greater installed power and half the number of turbines compared to the previous world's largest offshore wind farm – London Array
- Life extension
  - As assets are ageing, lifetime extension considerations are becoming increasingly important
  - Understanding foundation health is very important
- Increasing access windows

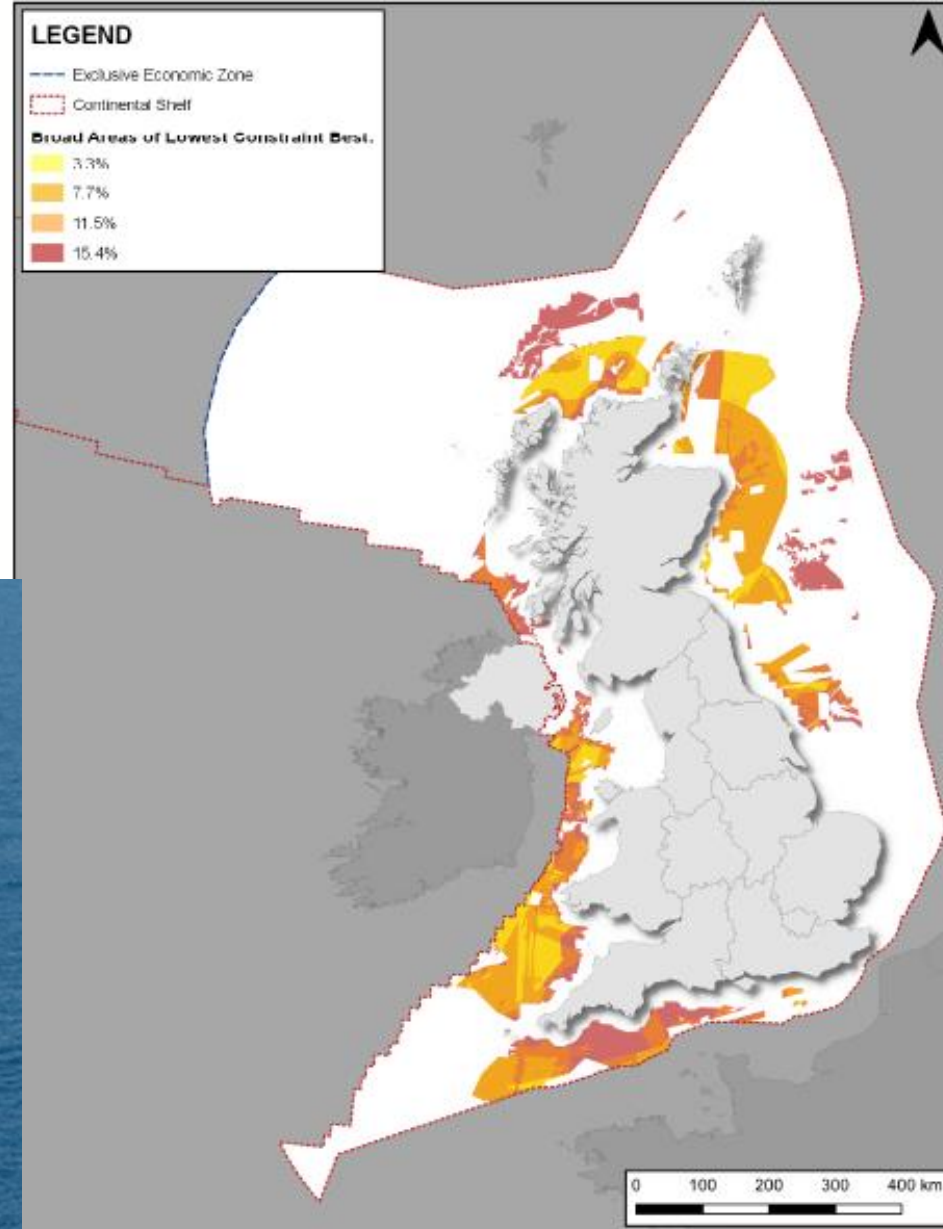


Type of Access	Vehicle/System	Sub Category	Significant Wave Height, $H_s$ [m]
Boat Landing	Crew Transfer Vessels (CTVs)	Mono-hull	1 – 1.2
		Catamaran	1.2 – 1.5
		Trimaran	1.5 – 1.7
		Small Waterplane Area Twin Hull (SWATH)	1.7 – 2
		Surface Effect Ship (SES)	1.8 – 2.2
	Systems that enhance access to the boat landing		2 – 2.5
Access to the Transition Piece (TP) Platform	Service Operation Vessel (SOV)/ Walk-to-Work Vessel	SOV Vessel	n/a
		SOV daughter craft	~1.2
	Motion compensated Systems	for transfer of personnel	1.5 – >4.5 <sup>1</sup>
		for transfer of components $1 \leq \text{weight (metric tonnes)} \leq 20$	3 – 4.5 <sup>1</sup>



## Celtic Sea Alliance

- Realising the Floating Offshore Wind opportunity.
- Spatial planning, innovation and the local supply chain.

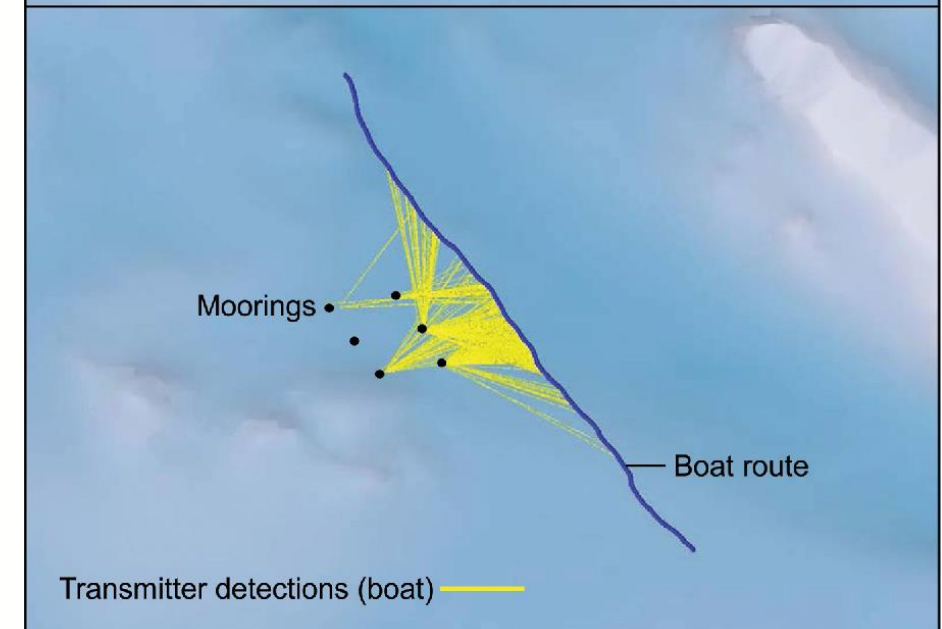
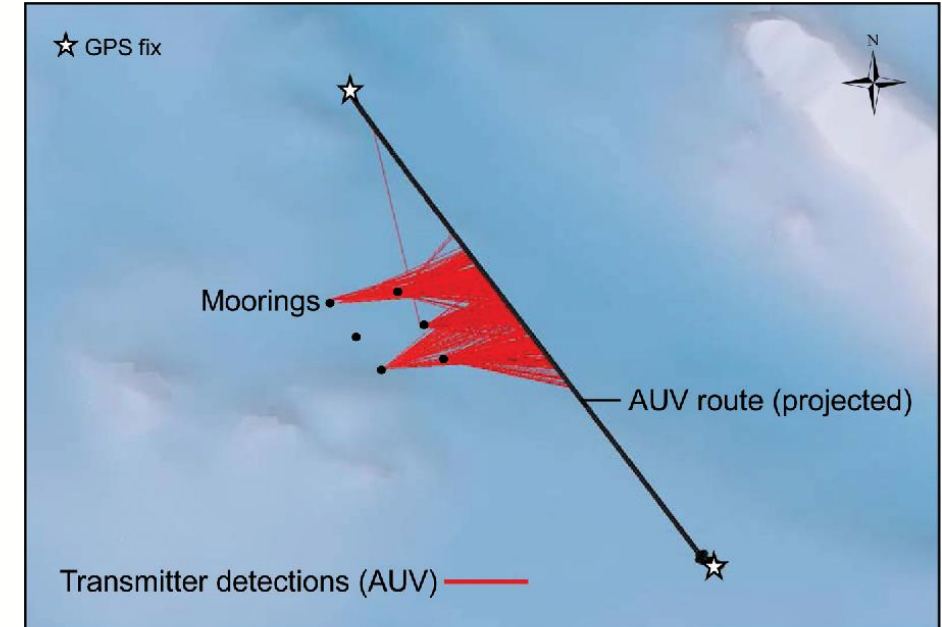
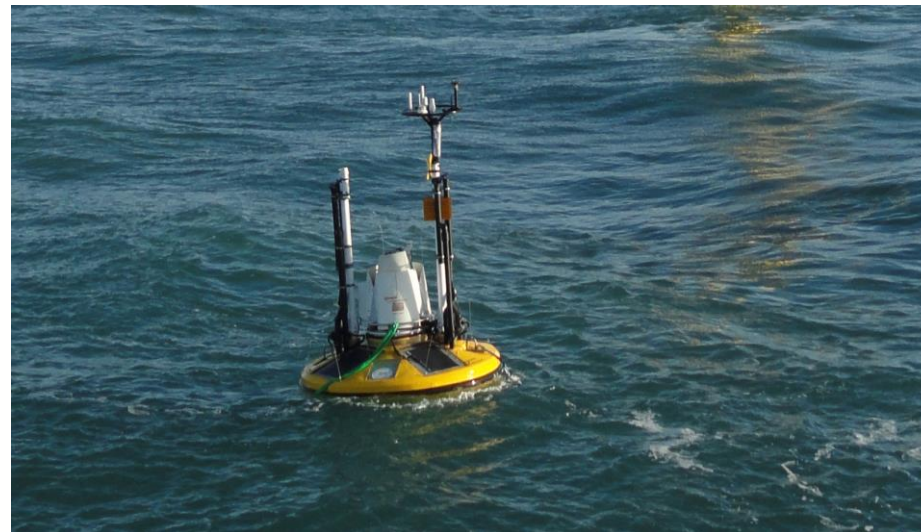
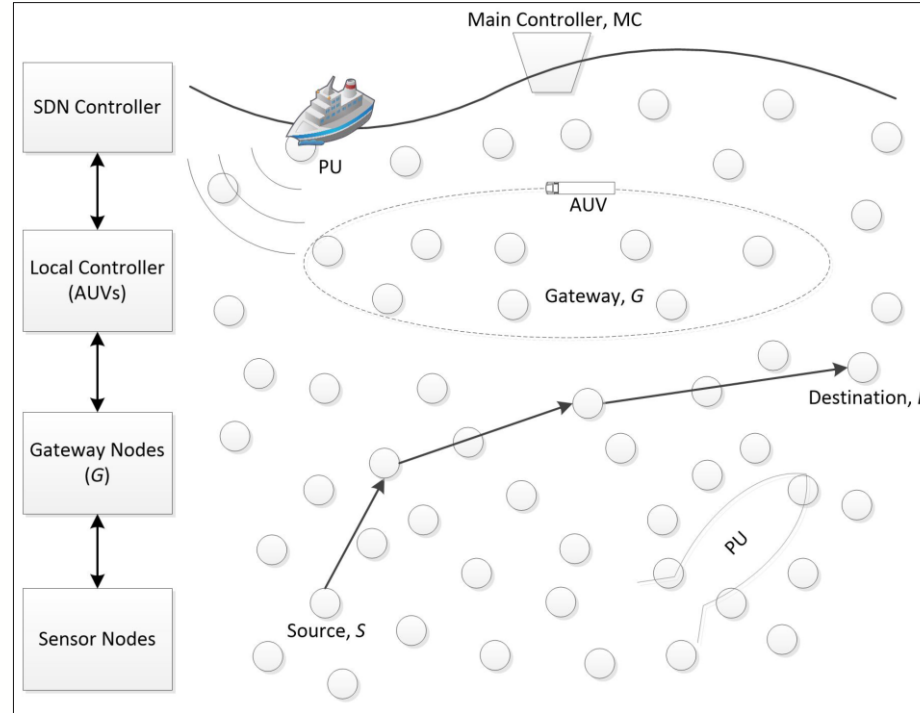


# Autonomous opportunities & challenges

- Further reduces the need for manned operations

## Challenges

- How is this tested and verified?
- How is data returned to the users?
- How to plan the optimal route (not unique to autonomous systems)
- Power requirements





Testing and validating tomorrow's robotic and autonomous maintenance solutions.

- Marine Robotics & Autonomous Systems Testing
- Contact systems testing



The Catapult's National Offshore Anemometry Hub (NOAH), off the coast of Blyth, Northumberland.





- The payload is a key differentiator of ROVs and AUVs

## Soil Machine Dynamics - Anemoi Project

- Developing a method for detecting and following buried cables in an offshore wind farm
- Supporting with research to understand different failure mechanisms of array cables
- Trialling of methodology in simulated seabed dock with buried cable



- Huge amount of work to watch and annotate ROV video streams
- Often just to advise actions on a few key findings

## ROVCO - AUV<sub>3D</sub> Project

- Creating 3d visualisation models of assets
- Generating actionable information rather than hours and hours of video
- Iterative testing in docks to develop the 3d models





- Increases efficiency, allows charging of AUV in situ, eliminates need for support vessel
- Facilitating technologies required
  - Power source
  - Data transmission

## Modus Seabed Intervention & Osbit Avison Project

- Vehicle recharging
- Upload of acquired data
- Downloading of new mission plans
- Trials in dry docks followed by offshore met mast

**MODUS**  
Seabed Intervention

**OSBIT**



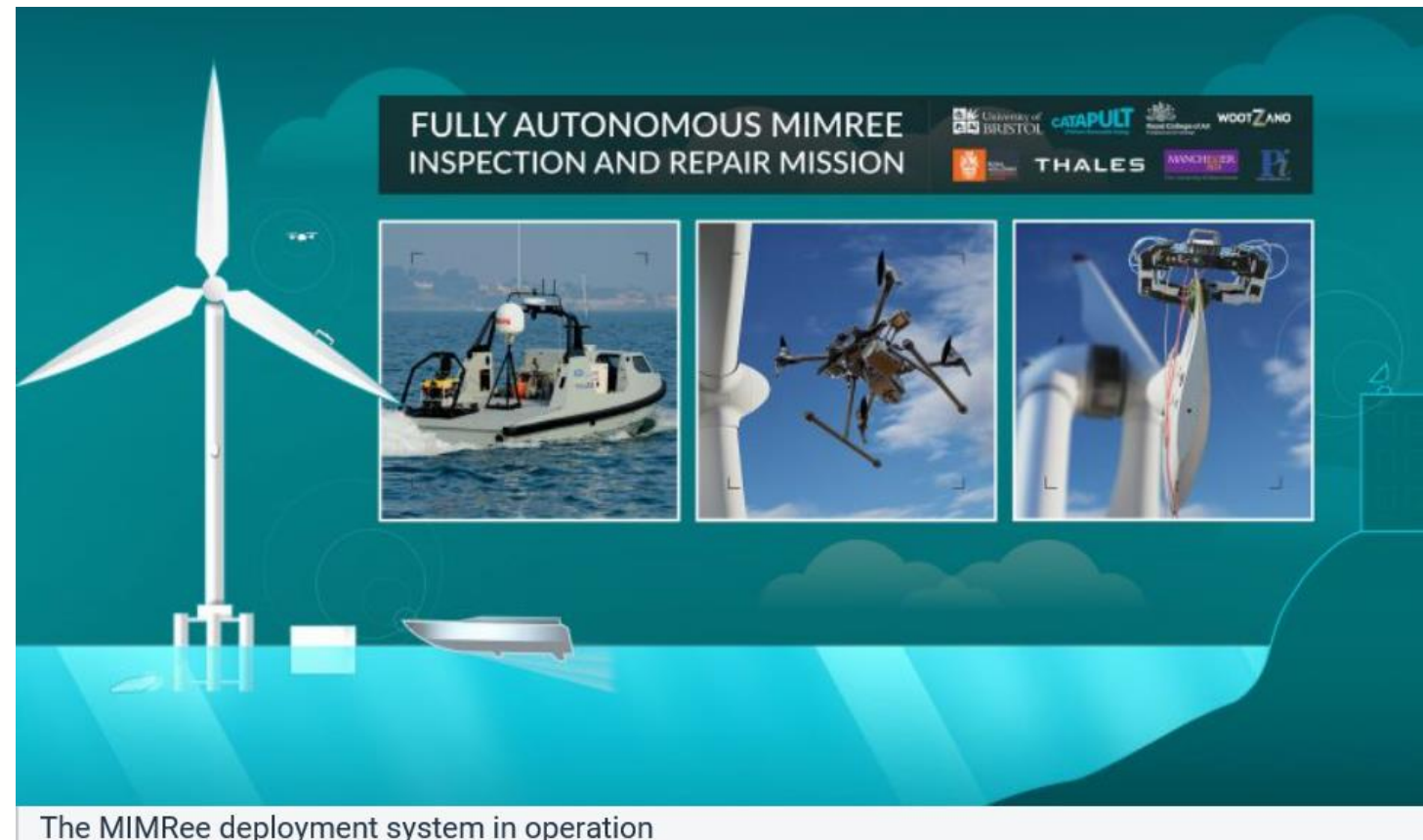
*Multi-Platform Maintenance, Inspection and Repair in Extreme Environments*, a project that was awarded funding by Innovate UK to develop and test a fully automated inspection and repair system for offshore wind farms.



THALES



WOOTZANO



[https://www.youtube.com/watch?time\\_continue=50&v=kQvN71bfTA4](https://www.youtube.com/watch?time_continue=50&v=kQvN71bfTA4)



# Blade bug & the Halycon Autonomous Vessel



Thales' Halcyon autonomous surface vessel will play a key role in MIMRee.

- Operating the World's most advanced fleet of autonomous vehicles.
- Ocean Infinity has applied proven systems at an unprecedented scale on board a single multi-purpose offshore vessel. The technology is precisely integrated into a comprehensive system for offshore survey, inspection, repair and recovery.



**MULTI-PURPOSE  
OFFSHORE VESSEL**  
SEABED CONSTRUCTOR

**UNMANNED  
SURFACE VEHICLE**  
USV



**AUTONOMOUS  
UNDERWATER VEHICLE**  
AUV



# Contact us

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Engage with us:



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CHINA